CMPT 720 - G100 Robotic Autonomy

Instructor(s): Mo Chen

Calendar Objective/Description:
Robotic Autonomy

Instructor's Objectives:
This course introduces fundamental concepts in robotics and related fields, including analytical methods for decision making, and machine learning in the context of robotics. Topics include modelling and simulation of robotic systems, optimization, optimal control, robotic safety, reinforcement learning, and robotic perception. Applications of the material include unmanned aerial vehicles and self-driving cars.

Prerequisites:
see go.sfu.ca

Topics:
- Modelling and simulation
- Optimization
- Optimal control
- Robotic safety
- Reinforcement learning
- Robotic perception

Grading:
Assignments – 40% Project proposal – 10% Project presentation and report – 50%

Recommended Books:
- Introduction to Autonomous Mobile Robots, R. Siegwart, I. R. Nourbakhsh, and D. Scaramuzza, MIT Press, 9780262015356
- Planning Algorithms, S. M. LaValle, Cambridge University Press, 9780521862059
- Convex Optimization, S. Boyd and L. Vandenberghe, Cambridge, 9780521833783
- Dynamic Programming and Optimal Control, D. P. Bertsekas, Athena Scientific, 9781886529434
- Reinforcement Learning: An Introduction, R. S. Sutton and A. G. Barto, MIT, 9780262039246

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